

How to build your robot

www.pib.rocks/build

assembly instructions for:

Neck

pib#4 advanced



PRINT BUILD DEVELOP YOUR OWN ROBOT



Printable and pre-assembled parts

Pib's neck consists of **13 printable parts** and is assembled in **10 steps.**

In order to construct the neck, you will need to print the parts as seen in the table.

Please note: For better readability we use the abbreviations in the tutorial: A50 instead of A50-Neck_housing.

We provide a screwdriver shaped like a pen in the box that includes the required hexagonal head. However, using a longer one can be useful

Printable parts
A71s-Inner_part_S
A72s-Top_part_S
A73-Cover_neck
A75s-R-Neck_Right_S
A75s-L-Neck_Left_S
A76-Neck_Middle
A81-Motor_shaft
A82-Neck_axis
A83-Motor_adapter_neck
A02-Face_neck_clamp
A77s-Neck_motor_wedge_S
A78s-Nodding_motor_wedge_S



Non-printable parts

You will also need the following non-printable parts from our pib.Box Master.

If you do not have it yet, you can buy in our shop https://shop.pib.rocks.

Non-printable parts
2 x M21 Ballbearings
2 x E07 MG996R servo
2 x M18 Metal-motor-Adapter
1 x M04 Ballbearing

Non-printable parts
13 x S01 M3 nuts
8 x S03 M3 8mm screws
8 x S04 M3 10mm screws
5 x \$05 M3 12mm screws
4 x \$06 M3 16mm screws
1 x S07 M3 18mm screws
4 x S08 M3 20mm screws
3 x \$11 M3 30 mm screws
1 x \$13 M3 40 mm screws



Printable parts - Overview











Printable parts - Overview









Build it better: our suggestion for assembling pib



We recommend **tools** for each step. These are a suggestion, you can of course also use other tools.



We have categorized each step according to its **difficulty** - from **1-5** (1 being the easiest, 5 the hardest)







We also show you which **non-printable parts** you need for each step



Step 0

Make sure all motors in this tutorial have their IDs set and calibrated according to tutorial "**step 1c motor** calibration"



Step 1

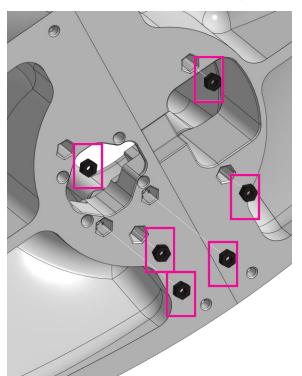


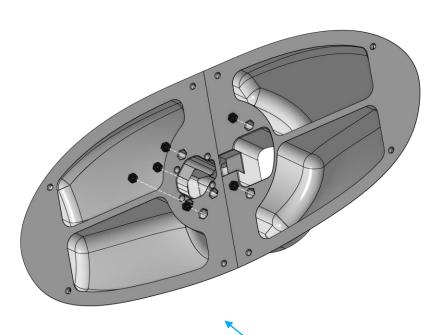






Insert **6 x nuts** in **A75s** in the shown spots.









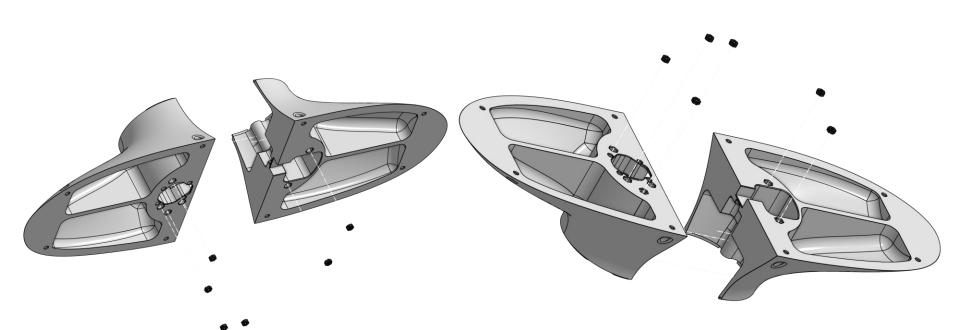








Insert **6 x nuts** in **A75s** in the shown spots.



Step 2



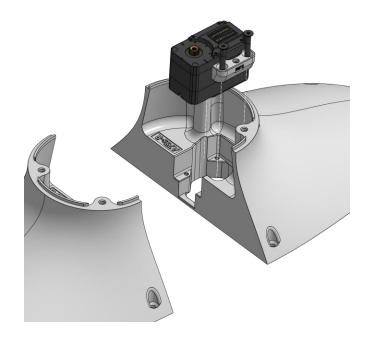






1:

Place 1 x E19 (STS3215) in A75 and use 2 x 12mm screws and A77s to fix it.









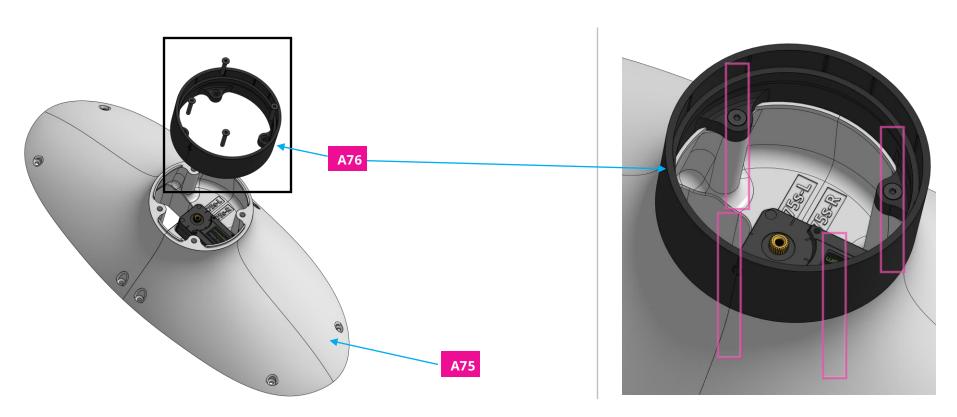








Connect A76 to A75s using 4 x M3 20mm screws.





Attach **3 x M3 nuts** and **1 x M18** to **A71**.

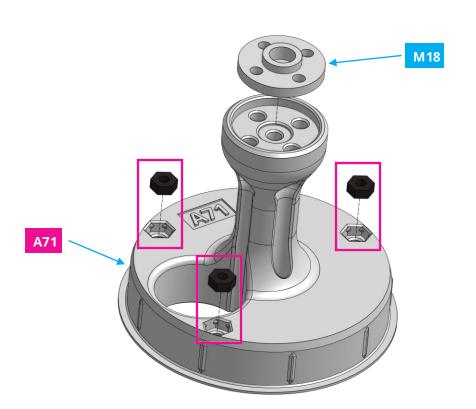














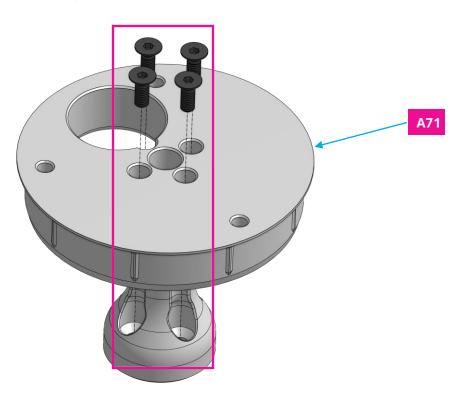








Fix M18 using 4 x M3 8mm screws.



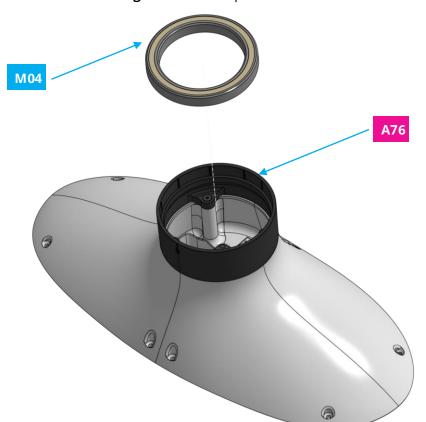


Step 5





Place 1 x M04 ballbearing in the shown spot of A76.









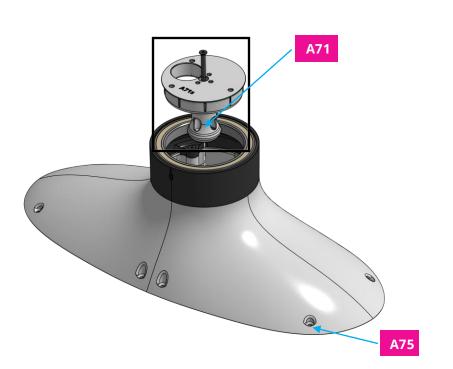
Connect A71s to A75 using 1 x M3 30mm screw.





















Connect A72 to the assembly using 2 x M3 30mm screw and 1 x M3 18mm screw.







Step 8a

Connect E07, M18 and A83 using 4 x M3 10mm screws.

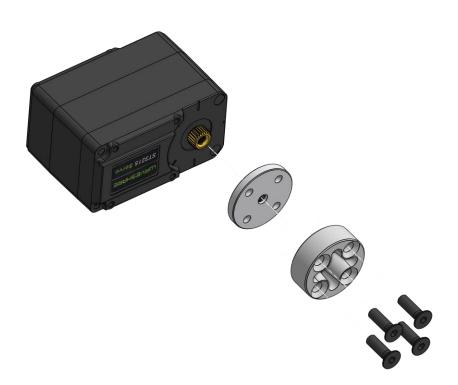
















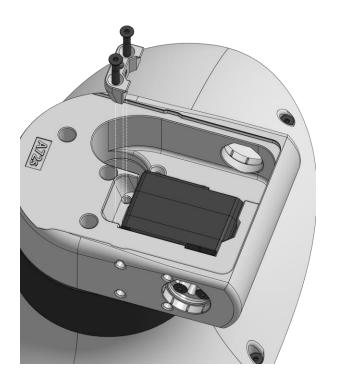
Step 8b

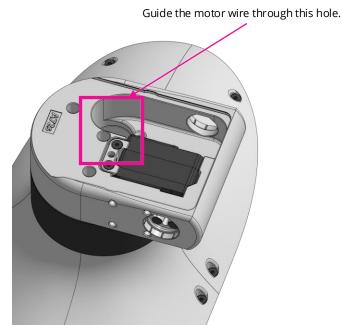






Insert E07 in A72 and fix it using 2 x M3 20mm screws.





The motor cable should hang out at the bottom of **A75**.

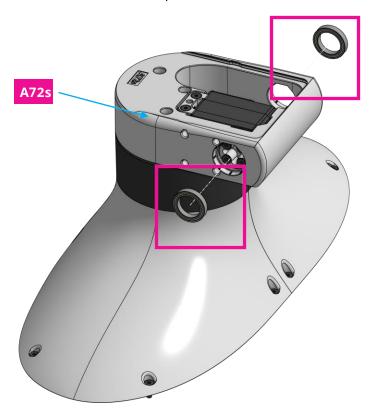








Insert 2 x M21 in the shown spots of A72s.



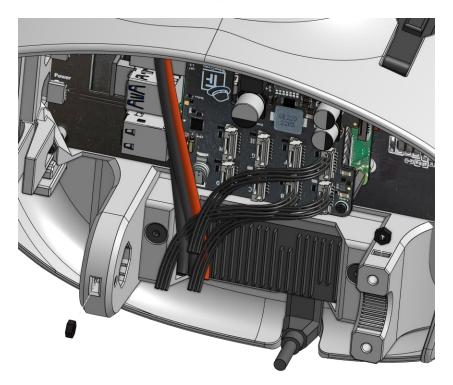


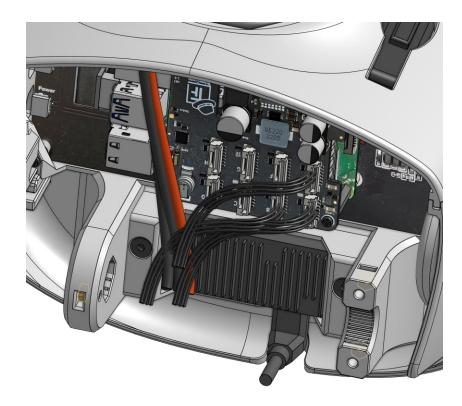


Step 9b

(d) 1

Insert **3 x M3 nuts** in the shown spots the head









Step 9c









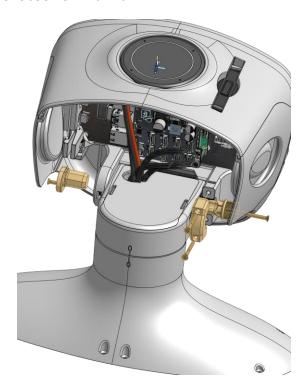


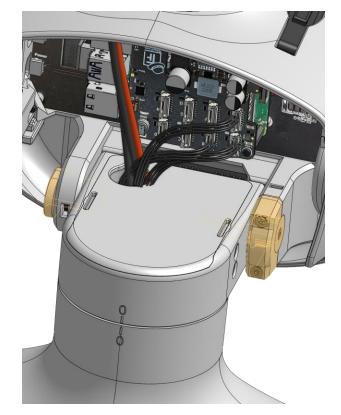




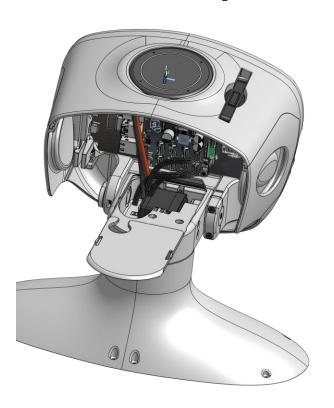
Connect head to neck using A81 and A82, 1 x M3 16mm screws and 1 x M3 40mm screws.

Then enclose **A81** with **A02**





Guide the wires from the head through the hole in **A72**, then close **A73**.







Congratulations

You did a great job, pib´s neck is assembled!







Do you need support?

Or do you need our pib.Box with all non-printable parts?
Or maybe you have some new ideas and improvements?
Please contact us.



team@pib.rocks
Send us an email.



discord.com/invite/GRdpyeDu7P Join us on Discord.



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