

How to build your robot

www.pib.rocks/build

assembly instructions for:

HEAD

v2024



PRINT BUILD DEVELOP YOUR OWN ROBOT



Printable and pre-assembled parts

Pib's head consists of **2 printable parts** and is assembled in **15 steps.**

In order to construct the head, you will need to print the parts as seen in the table.

Please note: For better readability we use the abbreviations in

the tutorial: A01 instead of A01-Face.

Printable parts

A01-Face

A03-Face_Plate



Non-printable parts

You will also need the following non-printable parts from our pib.Box Master.

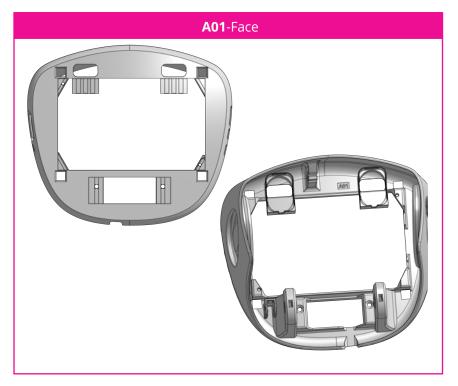
If you do not have it yet, you can buy in our shop https://shop.pib.rocks

1 x E01 Raspberry Pi_5
1 x E02 TinkerForge HAT (with 2-pole-connector)
1 x E04 OAK D-Lite
1 x E05 LCD screen with screws, distancer, speaker, connectors
1 x E12 USB Microphone
4 x S01 M3 nuts
2 x \$15 M2.5 12mm screws
4 x S14 M2.5x6mm
1 x USB to USB-C cable
90 cm black/red cable
1 x Micro-SD-card

Non-printable parts



Printable parts - Overview







Build it better: our suggestion for assembling pib



We recommend **tools** for each step. These are a suggestion, you can of course also use other tools.



We have categorized each step according to its **difficulty** - from **1-5** (1 being the easiest, 5 the hardest)

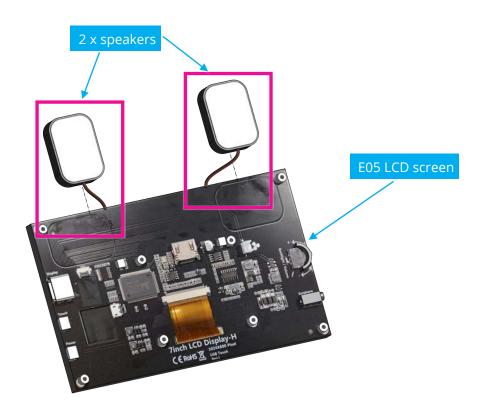


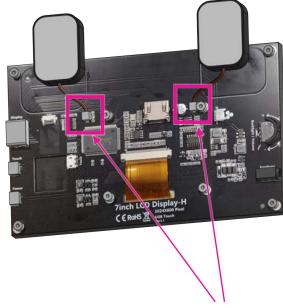




We also show you which **non-printable parts** you need for each step

Insert 2 x speakers (part of the screen package) into the shown spots in the E05 LCD screen.

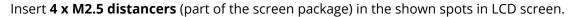


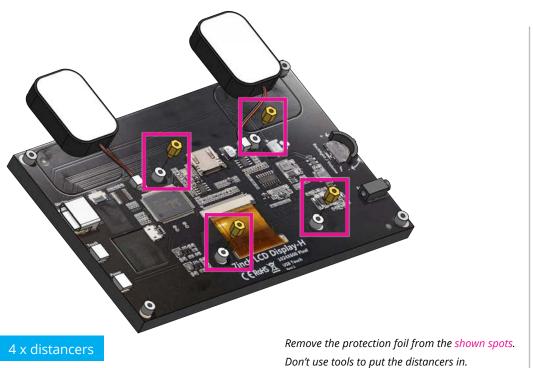


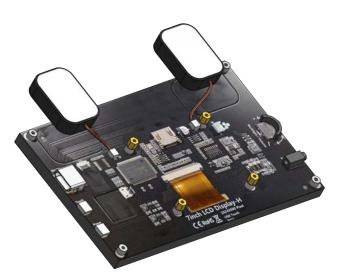
You can see some metal parts on one side of these wire connectors. This side has to face down towards the LCD screen.













(8)

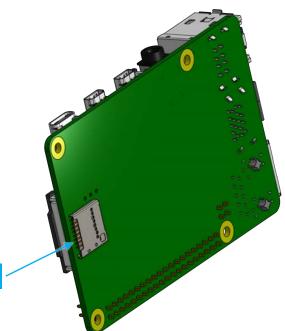


Insert the Micro-SD-card into the Raspberry Pi.



Before you insert the SD card make sure you have installed the pib.software on it.

You can find the tutorial here: https://pib.rocks/build/how-to-install-raspberry-pi/



Insert SD-card here



Step 4a

(8)

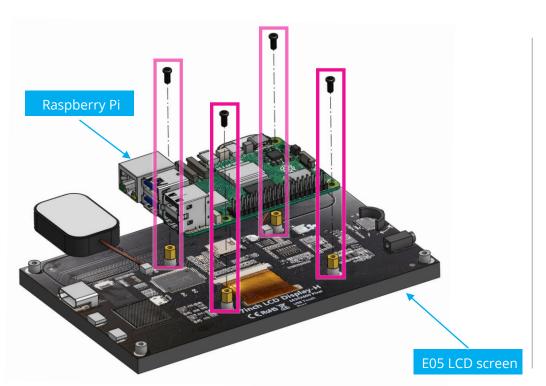






1x

Place the **Raspberry Pi** on top of the **LCD screen** and fix it with with **4 x M2.5 6mm screws** (part of the screen package).





Step 4b

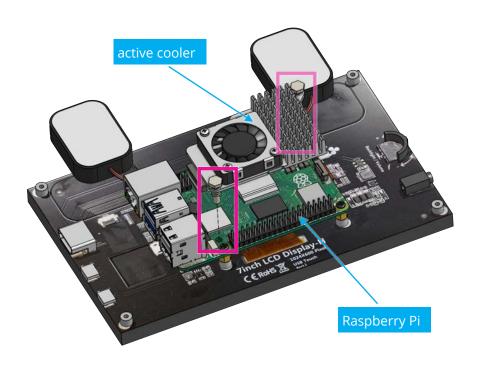
Attach E18 active cooler to Raspberry Pi.













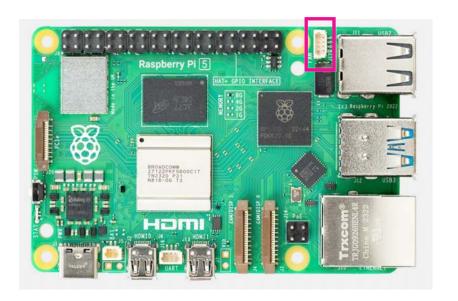








Make sure that **E18 active cooler's** fan wire is connected to **"fan"** slot in **Raspberry Pi**.







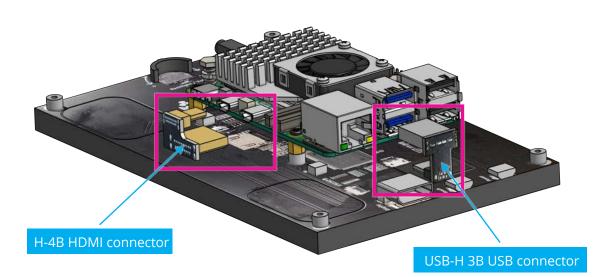


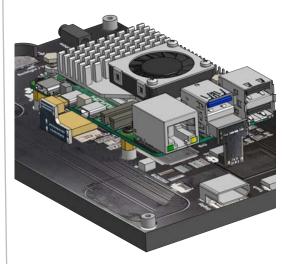


Now, we have to connect the **Raspberry Pi** and the **LCD screen** electronically.

For this, there are two connectors (part of the screen package):

- **USB-H 3B** USB connector (responsible for touch screen functionality)
- **H-4B** HDMI connector (responsible for video signal)



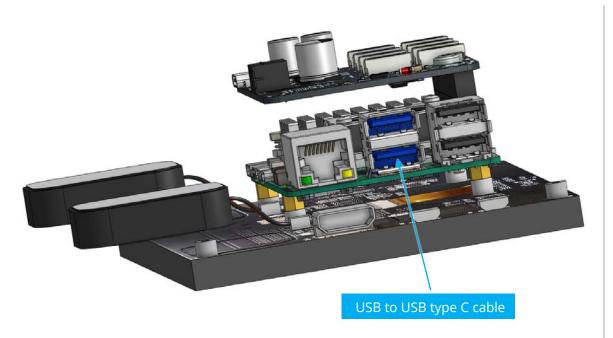


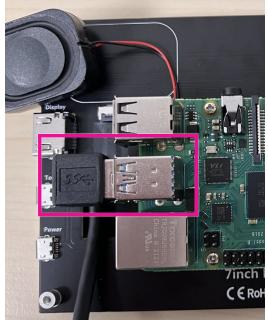






Connect **"USB to USB type-c"-cable** in the shown spot for usage of the camera.





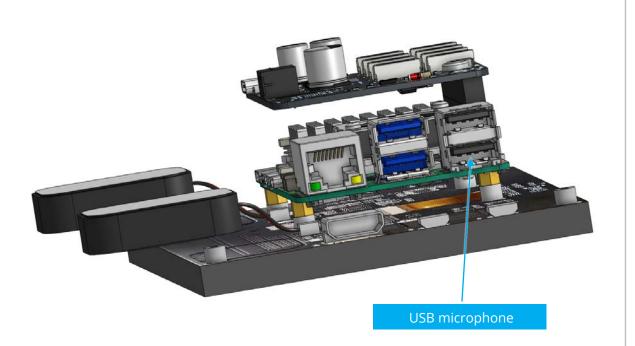


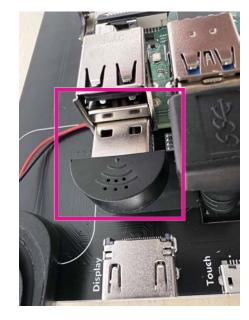




1x

Connect the **USB microphone E12** to the shown port of the Raspberry Pi.



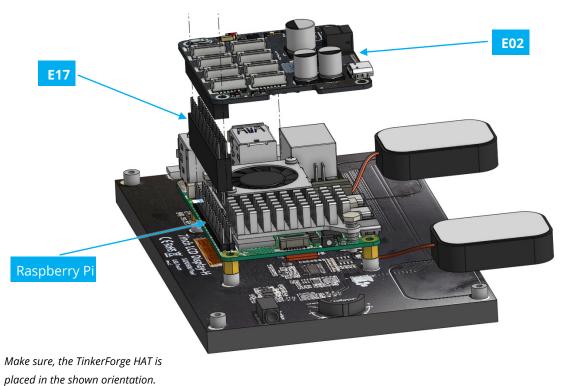








Attach the **E02 TinkerForge HAT** to **Raspberry Pi** using the **E17 GPIO extender**.







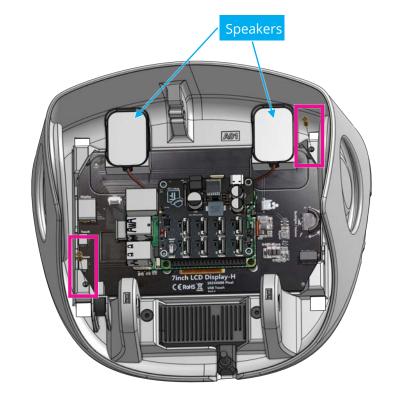






Insert the assembly from previous steps to **A01** and fix it using **2** x **M2.5 12mm screws** (part of the screen package). Place the speakers in the shown spots of **A01**.











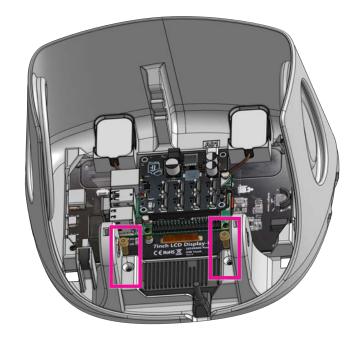






Insert the Oak-D-lite camera into A01 and tighten it using 2 x M4 10mm screws.









Connect the **"USB to USB-type-C"-cable** from **step 6** into the shown spot of the camera.





USB to USB-type-C cable

(d) 1

Finally, connect A03 to A01





Congratulations

You did a great job, pib´s head is assembled!







Do you need support?

Or do you need our pib.Box with all non-printable parts?
Or maybe you have some new ideas and improvements?
Please contact us.



team@pib.rocks
Send us an email.



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