

# How to build your robot

www.pib.rocks/build

assembly instructions for:

# **NECK Version PRO**

v2024







## **Neck variations of pib**

Pib's neck has 3 variations:

- Rookie: simple with 1 degree of freedom (left and right movement)
- Pro: intermediate with 2 degrees of freedom (up and down + left and right movement)
- and ultimate: advanced with 3 degrees of freedom.

This tutorial describes how to build the **pro variation**, which is the default one.





## **Printable and pre-assembled parts**

Pib's neck consists of **9 printable parts** and is assembled in **10 steps.** 

In order to construct the neck, you will need to print the parts as seen in the table.

Please note: For better readability we use the abbreviations in the tutorial: A50 instead of A50-Neck\_housing.

Printable parts	
A71-Inner_part	
A72-Top_part	
A73-Cover_neck	
A74-Motor_shaft (2x)	
A75-R-Neck_Right	
A75-L-Neck_Left	
A76-Neck_Middle	
A77-Motor_Adapter_Neck	



# Non-printable parts

You will also need the following non-printable parts from our pib.Box Master.

If you do not have it yet, you can buy in our shop https://shop.pib.rocks.

Non-printable parts
2 x <b>M03</b> Ballbearings
2 x <b>E07</b> MG996R servo
2 x <b>M18</b> Metal-motor-Adapter
1 x <b>M04</b> Ballbearing

Non-printable parts
13 x <b>S01</b> M3 nuts
8 x <b>S03</b> M3 8mm screws
8 x <b>S04</b> M3 10mm screws
5 x <b>S05</b> M3 12mm screws
4 x <b>S06</b> M3 16mm screws
1 x <b>S07</b> M3 18mm screws
4 x <b>S08</b> M3 20mm screws
3 x <b>S11</b> M3 30 mm screws
1 x <b>S13</b> M3 40 mm screws



# **Printable parts - Overview**











# **Printable parts - Overview**









## Build it better: our suggestion for assembling pib



We recommend **tools** for each step. These are a suggestion, you can of course also use other tools.



We have categorized each step according to its **difficulty** - from **1-5** (1 being the easiest, 5 the hardest)



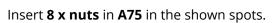


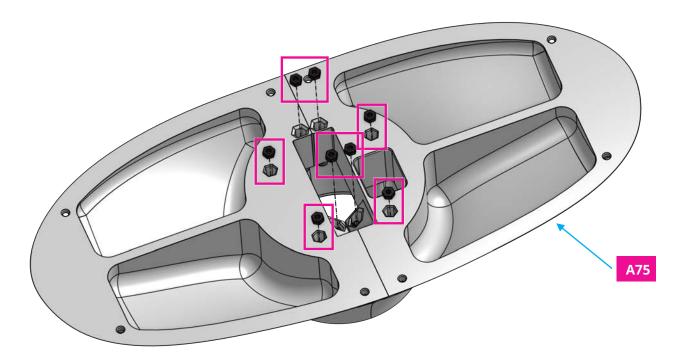


We also show you which **non-printable parts** you need for each step





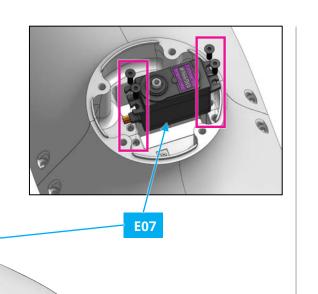






A75

Place 1 x E07 (MG996R) in A75 and use 4 x 12mm screws to fix it.







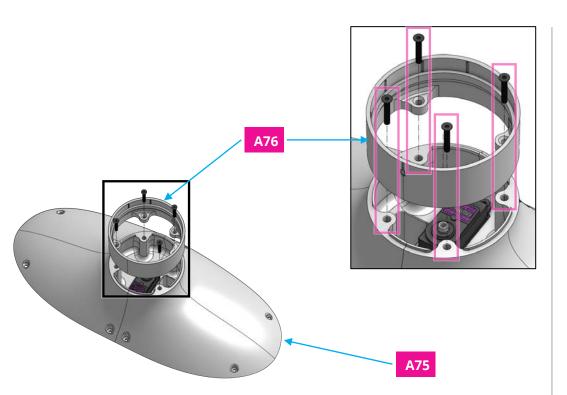








Connect A76 to A75 using 4 x M3 20mm screws.







#### Attach 3 x M3 nuts and 1 x M18 to A71.

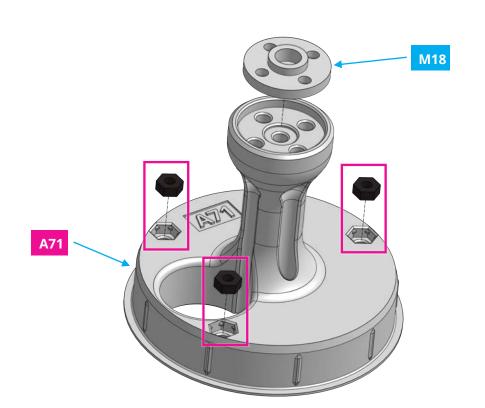














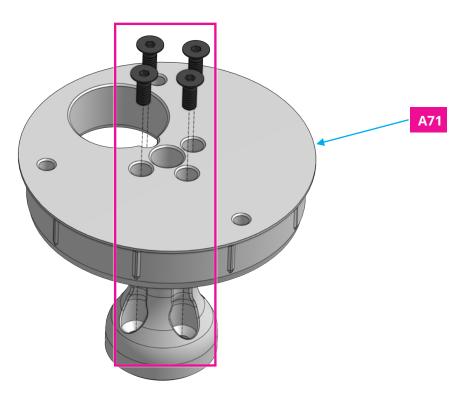


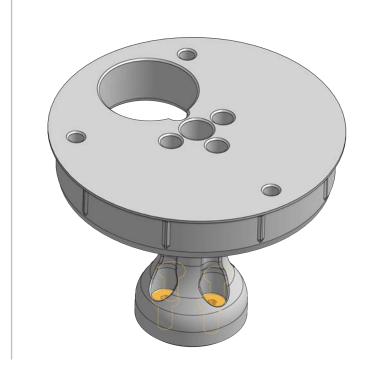






Fix M18 using 4 x M3 8mm screws.

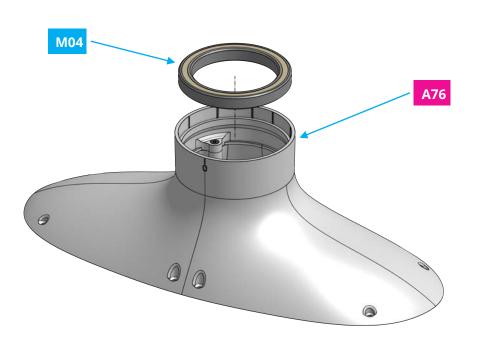








Place **1 x M04 ballbearing** in the shown spot of **A76**.



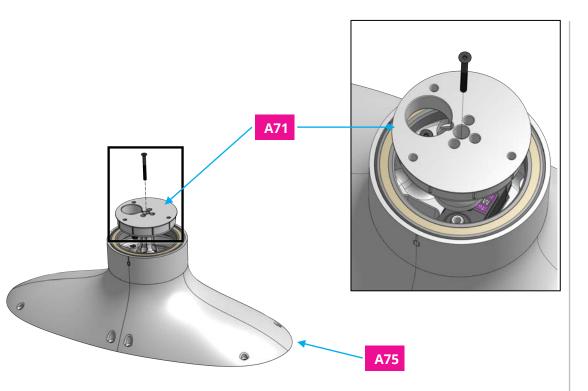








#### Connect A71 to A75 using 1 x M3 30mm screw.





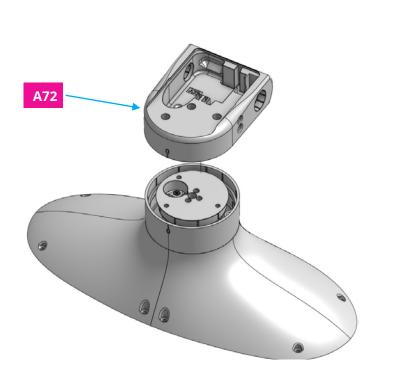


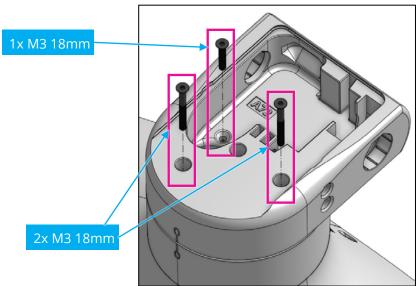






Connect A72 to the assembly using 2 x M3 30mm screw and 1 x M3 18mm screw.







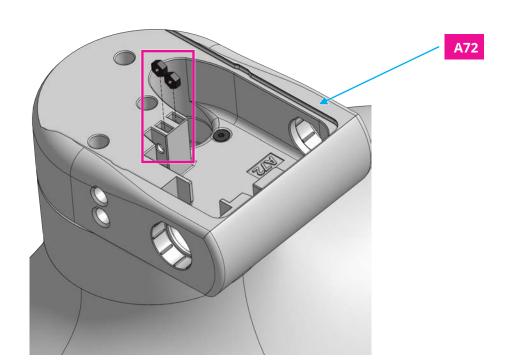
#### Insert 2 x M3 nuts In A72.













### Step 9a

Connect **E07**, **M18** and **A77** using **4 x M3 8mm screws**.



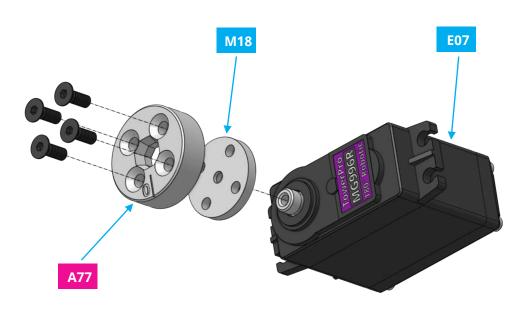














### Step 9b

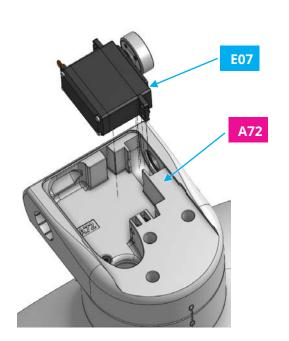


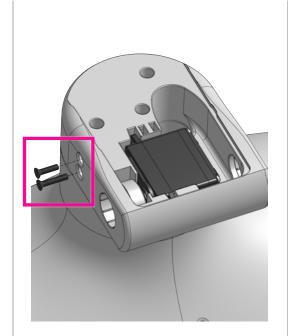


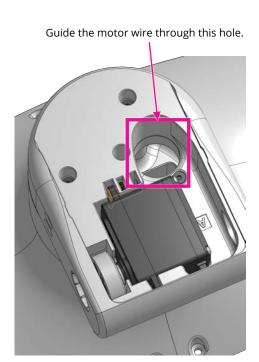




Insert E07 in A72 and fix it using 1 x M3 12mm and 1 x M3 16mm screws.







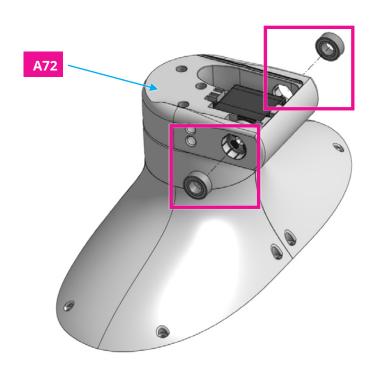
The motor cable should hang out at the bottom of **A75**.







Insert 2 x M03 in the shown spots of A72.











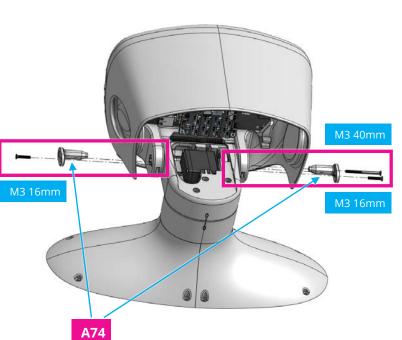






Connect head to neck using 2 x A74, 2 x M3 16mm screws and 1 x M3 40mm screws.

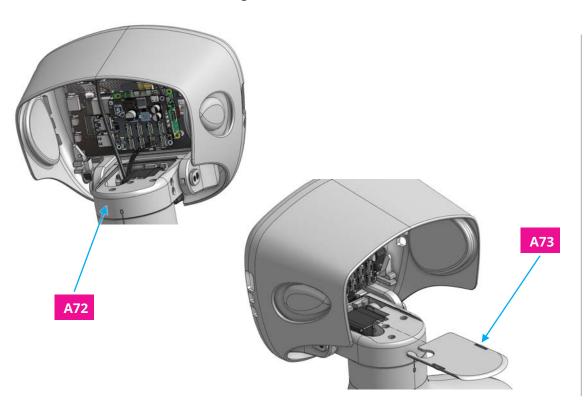








Guide the wires from the head through the hole in A72, then close A73.







# Congratulations

You did a great job, pib's neck is assembled!







## Do you need support?

Or do you need our pib.Box with all non-printable parts?
Or maybe you have some new ideas and improvements?
Please contact us.



team@pib.rocks
Send us an email.



**discord.com/invite/GRdpyeDu7P** Join us on Discord.



**shop.pib.rocks**Order non-printable parts for pib.