

How to build your robot

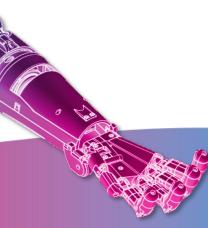
www.pib.rocks/build

assembly instructions for:

Hand and arm ASSEMBLY



your own robot!





Printable parts

In order to assemble the hand to pibs arm you will at least need to build the fingers, hand and forearm first.

You can find all our tutorials on pib.rocks/build

Tutorials on pib.rocks

https://pib.rocks/build/how-to-build-pibs-finger/

https://pib.rocks/build/how-to-build-pibs-**hand**/

https://pib.rocks/build/how-to-build-pibs-**forearm**/

Printable parts

2 x C50-Wrist_joint_connector



Non-printable parts

You will also need the following non-printable parts from our pib.Box Master.

If you do not have it yet, you can buy in our shop https://shop.pib.rocks.

Non-printable parts

2 x **S01** M3 nuts

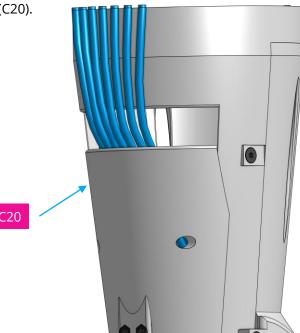
1 x **M08** metal rod

2 x **S09** 22 mm screws



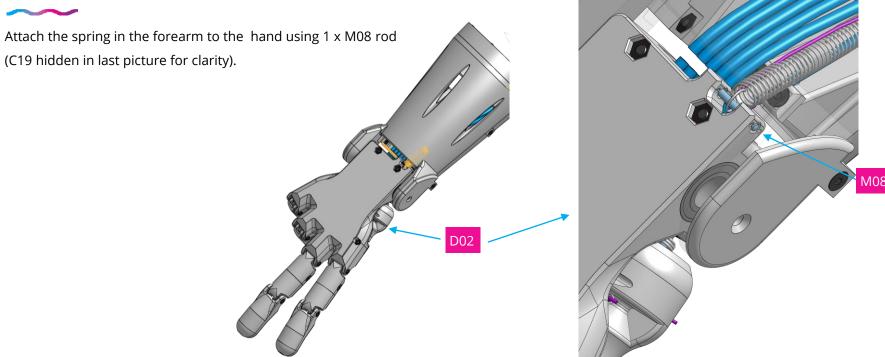
Step 1

Guide the tubes coming out of the hand through the shown part of the forearm (C20).





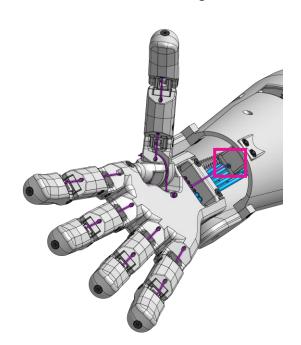
Step 2

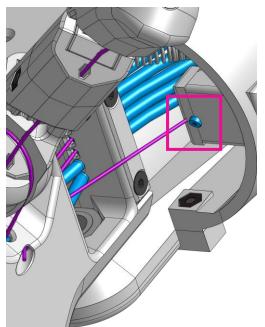




Step 3

Insert the loose fluorocarbon string (for wrist motion) coming out of hand into the teflon tube fixed in forearm.

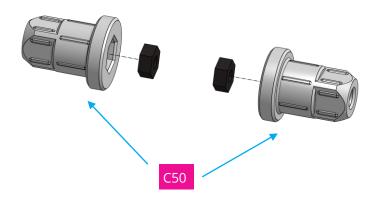






Step 4a

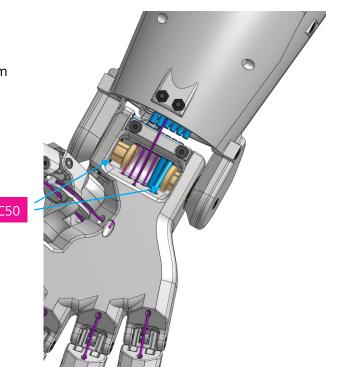


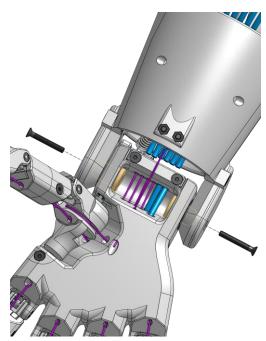




Step 4b

Use both C50 to connect hand and forearm and fix them using 2 x 22mm screws.



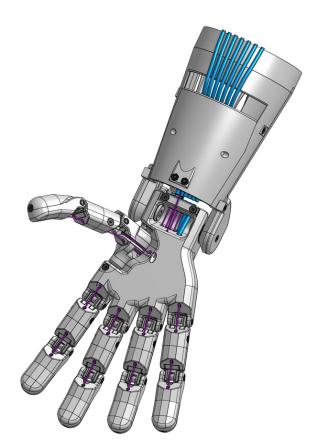




Congratulations



You did a great job. Pib´s hand is assembled to pib´s arm.





Do you need support?

Or do you need our pib.Box with all non-printable parts?
Or maybe you have some new ideas and improvements?
Please contact us.



team@pib.rocks
Send us an email.



discord.com/invite/GRdpyeDu7P Join us on Discord.



shop.pib.rocksOrder non-printable parts for pib.