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How to build your robot

www.pib.rocks/build

instructions for: MOTOR CALIBRATION



You Print Build Develop

your own robot!

instructions for: MOTOR CALIBRATION

Step 1

Connect servo motor to be calibrated to E03 Servo_bricklet.





Step 2a

Connect power to E03 Servo_bricklet using 40cm power cable, input power should be E13 connected to power supply.







Step 2b

Connect power to E03 Servo_bricklet using 40cm power cable, input power should be E13 connected to power supply.









Step 3

Connect bricklet to E02 Tinkerforge_hat in head to E03Servo_bricklet with cable loose from head tutorial.





Step 4a

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Open Brick viewer application in head.





Step 4b

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Click connect and navigate to servo bricklet 2.0 tab.





Step 4c

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Select all servos from menu and change pulse from 1000 to 700 and 2000 to 2500, and finaly type 0 in position then click enter (try to keep servo motor connected until you finish assembling it to prevent shaft from moving).

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UID: SFK FW Version: 2.0	0.0 Timeouts: 0 Status LED:	Show Status V Reset	More	UID: SFK FW Version: 2	2.0.0 Timeouts: 0 Status	ED: Show Status	 ✓ Reset 	More
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