



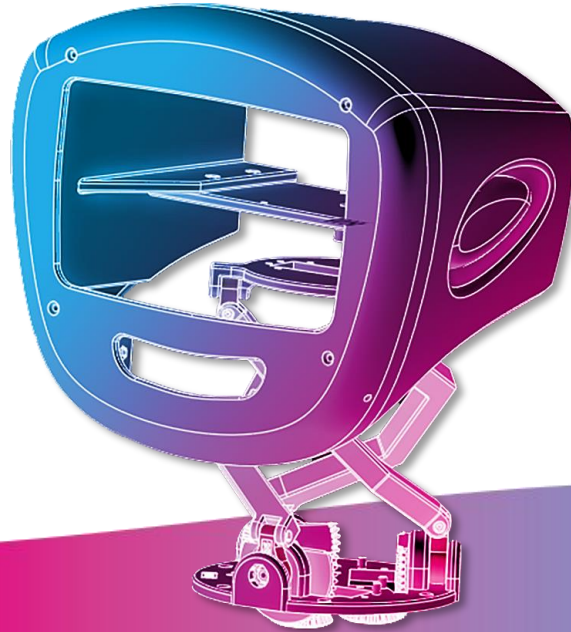
How to build your robot

www.pib.rocks/build



assembly instructions for:

HEAD



You
Print
Build
Develop

your own robot!

Printable parts



Pib's head consists of **3 printable parts** - and the assembled parts from the neck tutorial - and is assembled in **xx steps**.

In order to construct the head, you will need to print the parts as seen in the table and also first assemble the neck part.

Please note: For better readability we use the abbreviations in the tutorial: A01 instead of A01-Face.

Printable parts

A01-Face

A02-Head_board_mount

A03-Face_Plate

A14-Neck_ballbearing_holder

4 x **A15**-Neck_ballbearing_holder_leg

Non-printable parts



You will also need the following non-printable parts from our pib.Box Master.

If you do not have it yet, you can buy in our shop

<https://shop.pib.rocks>

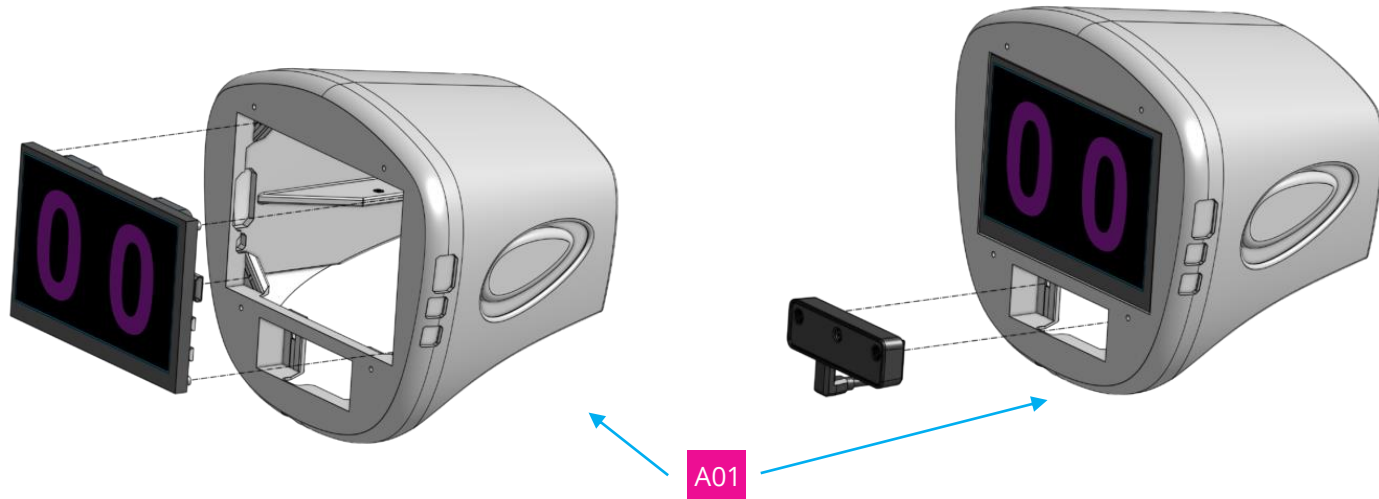
Non-printable parts
E01 Raspberry Pi
E02 TinkerForge HAT
E04 OAK D-Lite Camera
E05 LCD display
4 x M13 Distancer
4 x M14 Distancer_2
M03 Ballbearing
22 x S01 nuts
4 x S10 25mm screws
4 x S11 30mm screws

Non-printable parts
4 x S04 10mm screws
6 x S05 12mm screws
4 x S06 16mm screws
S08 20mm screws

Step 1



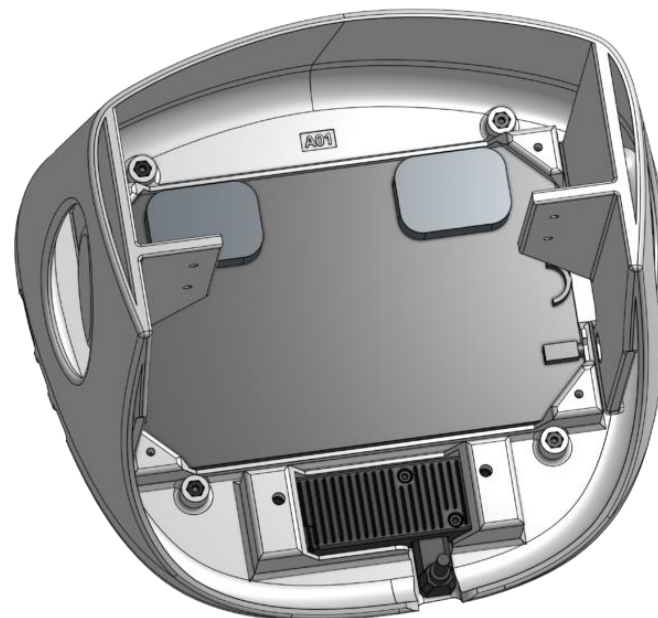
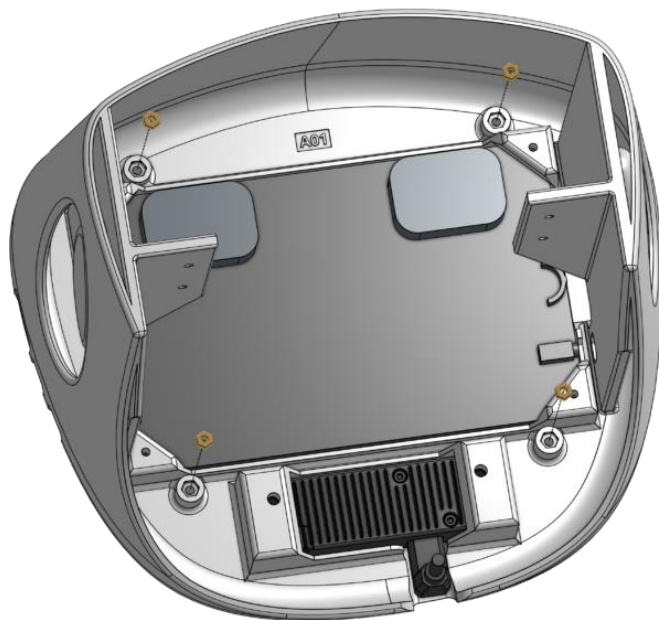
Insert the LCD display and the OAK-D Lite camera through the shown spots in A01.



Step 2



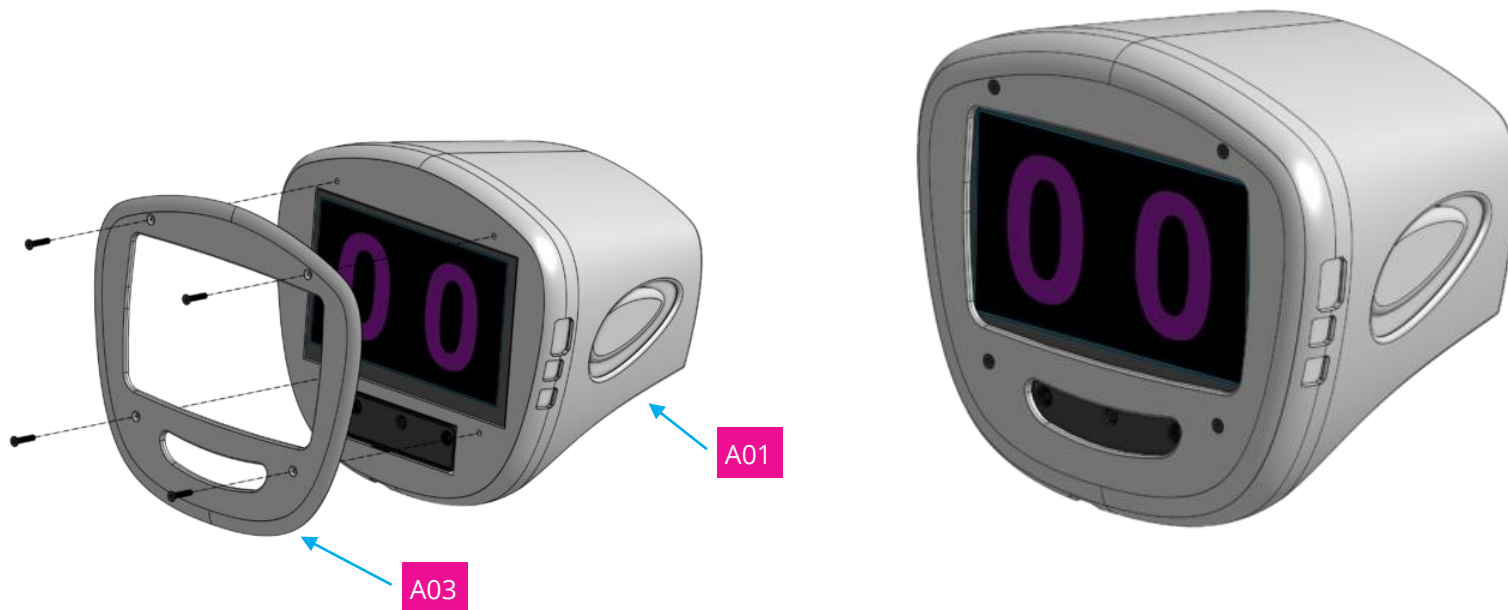
Place 4 x nuts in the shown spots in A01.



Step 3



Attach A03 to A01 using 4 x 16mm screws.

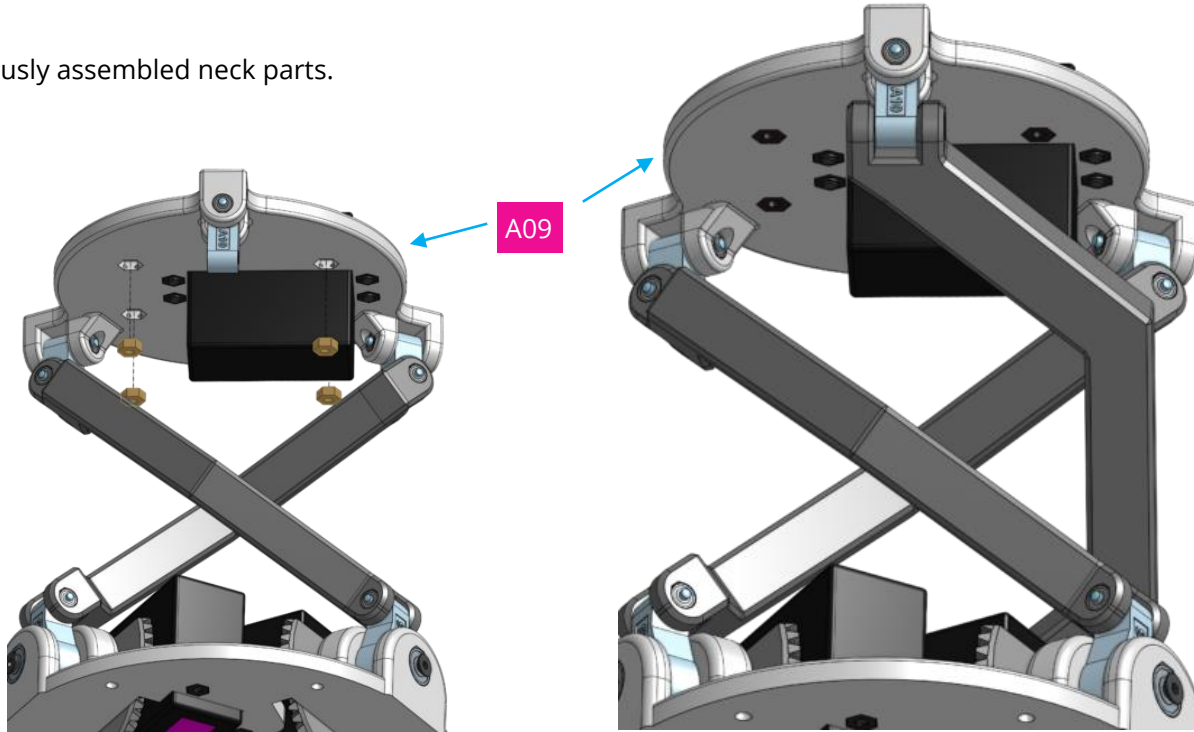


Step 4



Now you will need your previously assembled neck parts.

Place 4 x nuts in A09.



Step 5



Place 4 x nuts in the shown places of A02.

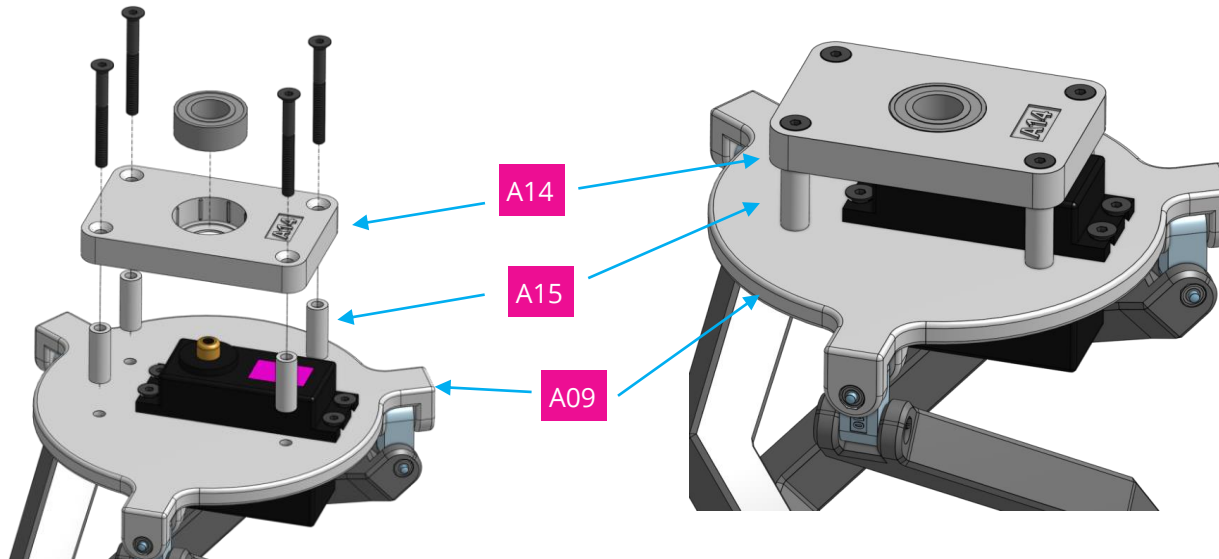


View from below

Step 6a



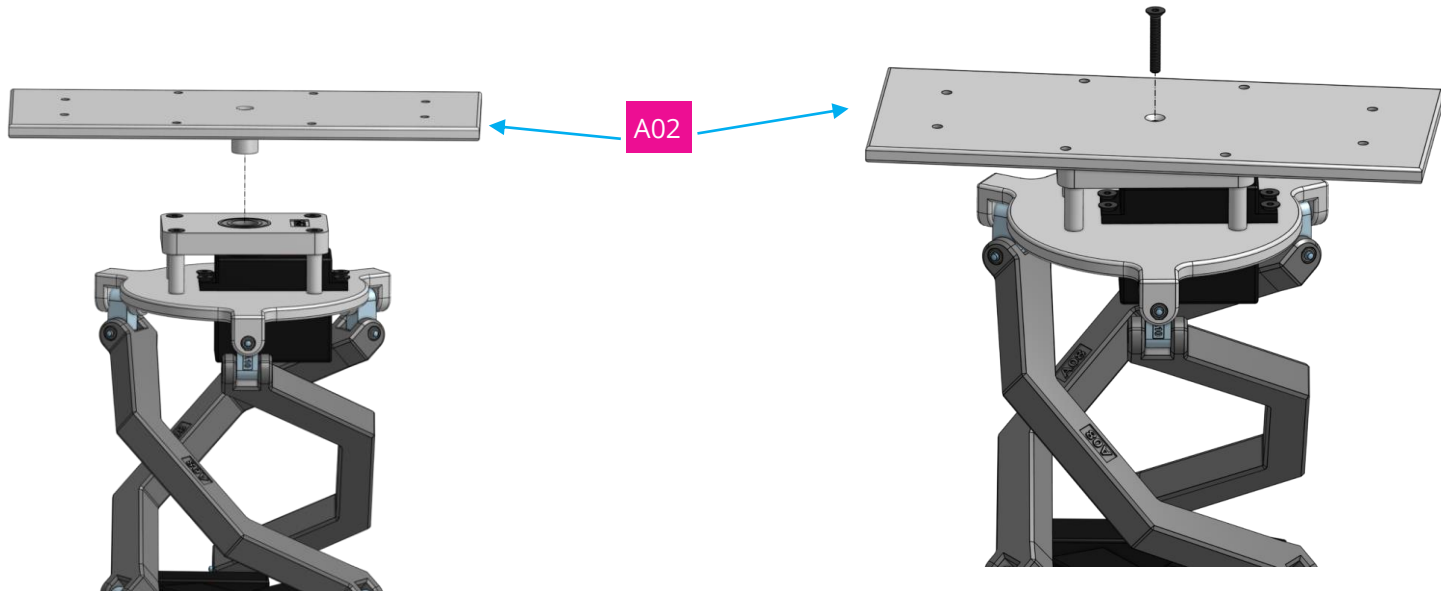
Connect A02 to A09 using A14 and 4 x A15 by following the shown sequence. You will need 4 x 30mm screws to connect the parts. Additionally, add 1 x M03 ballbearing in the shown spot.



Step 6b



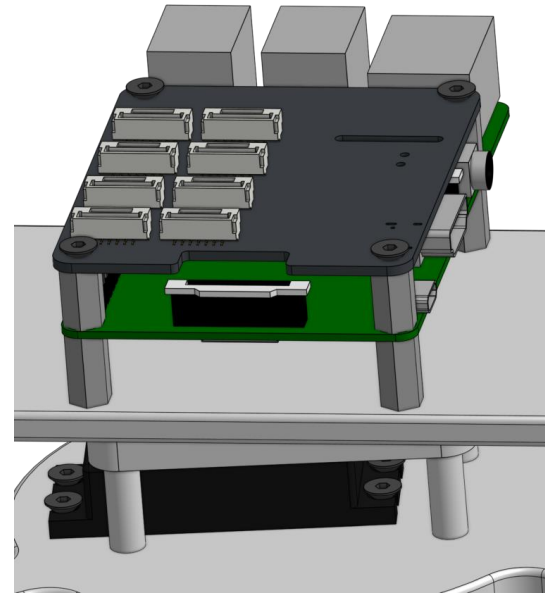
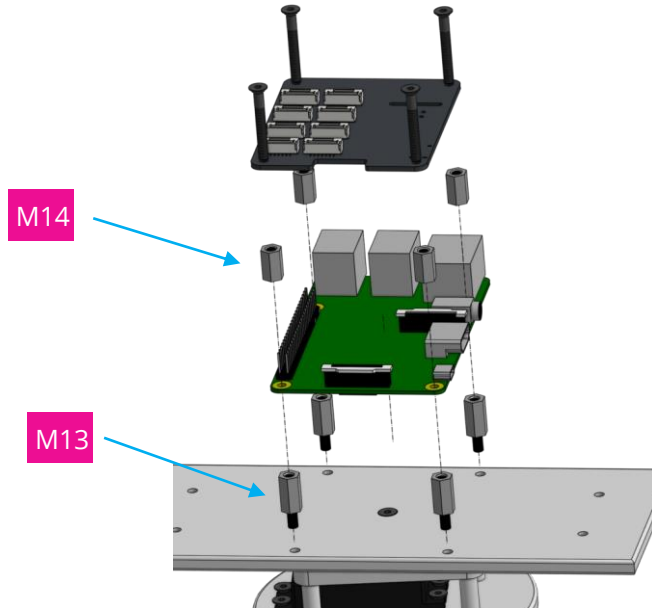
Connect A02 to A09 using A14 and 4 x A15 by following the shown sequence. Use 1 x 20mm screw to connect A02 to the assembly



Step 7



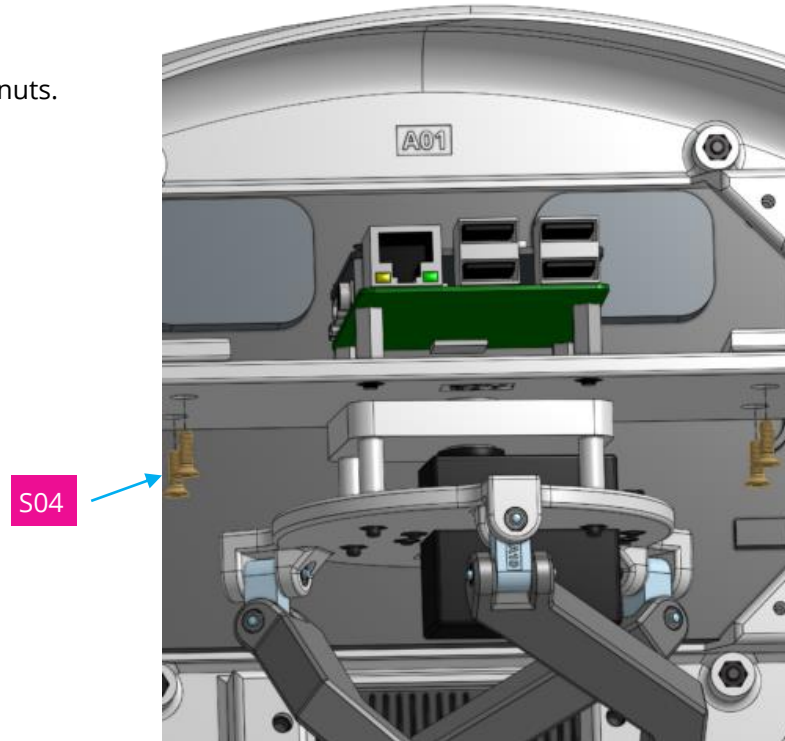
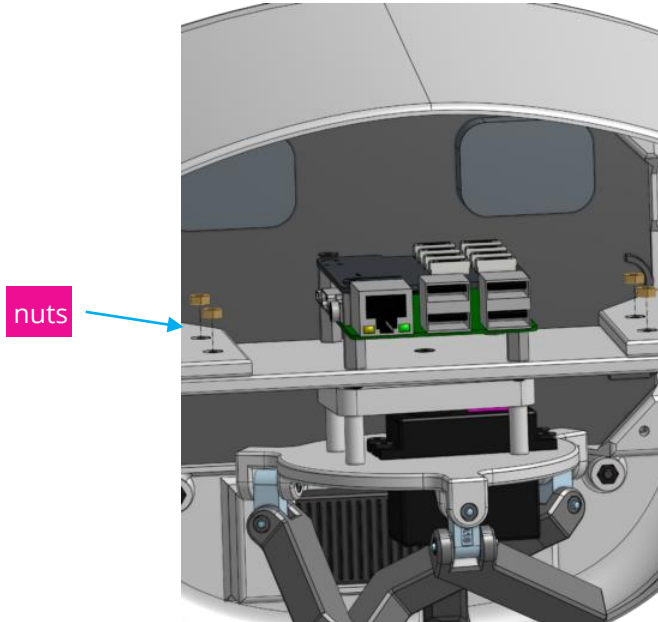
Connect Raspberry Pi and TinkerForge Hat to A02 using 4 x M13 Distancer, 4 x M14 Distancer and 4 x 25mm screws.



Step 8



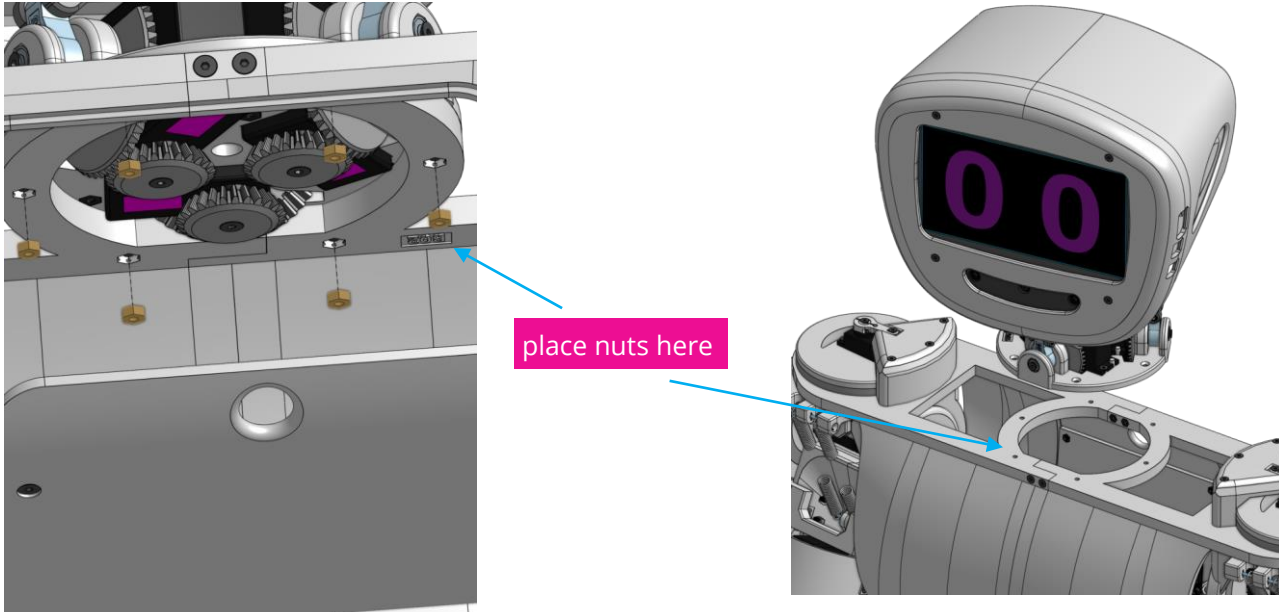
Connect face assembly to neck using 4 x 10mm screws and 4 x nuts.



Step 9a



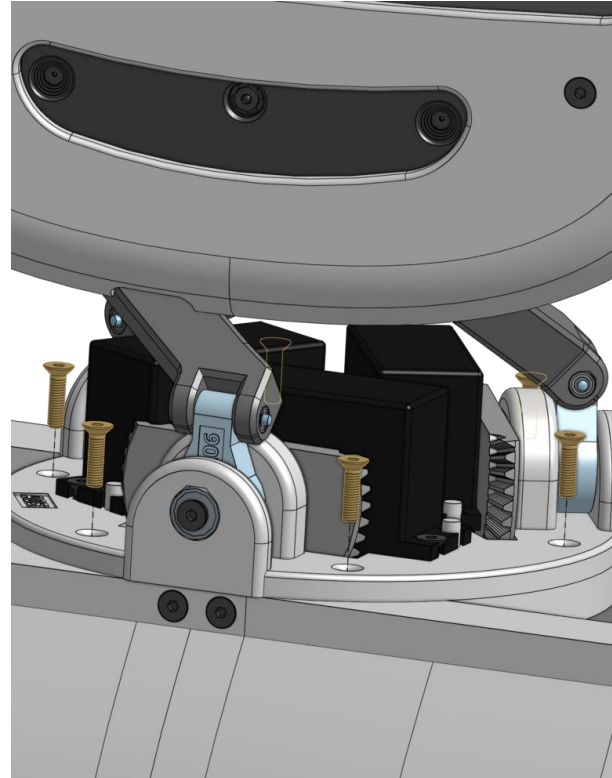
Connect the head-neck-assembly to the assembled pib from previous tutorials using 6 x 12mm screws and 6 x nuts.



Step 9b



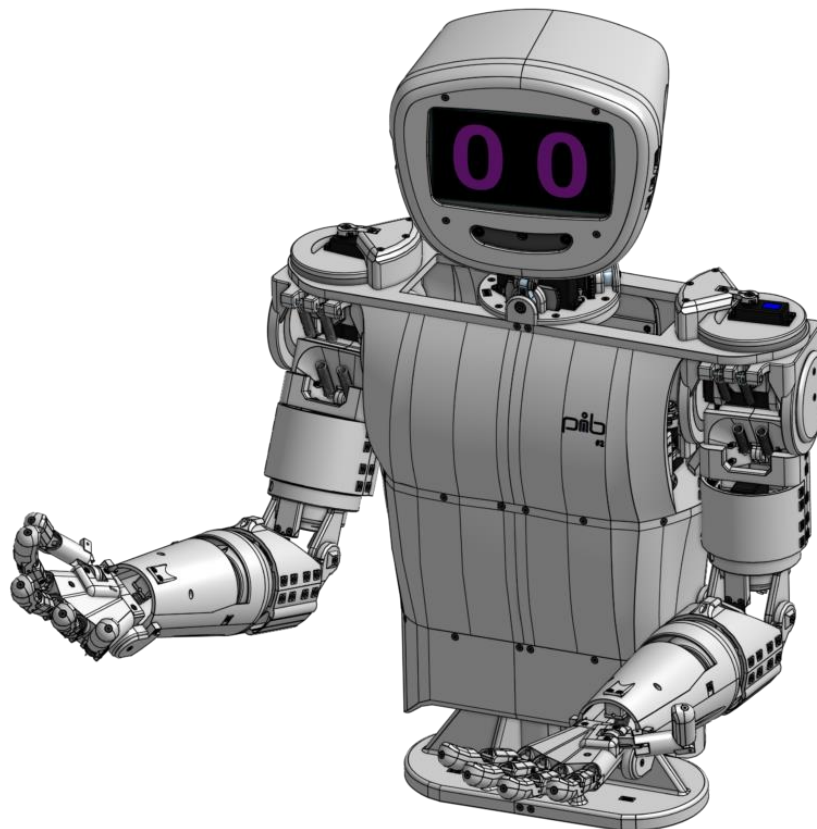
Connect the head-neck-assembly to the assembled pib from previous tutorials using 6 x 12mm screws and 6 x nuts.



Congratulations



You did a great job, your pib is assembled!



Do you need support?



Or do you need our pib.Box with all non-printable parts?
Or maybe you have some new ideas and improvements?
Please contact us.



team@pib.rocks
Send us an email.



discord.com/invite/GRdpyeDu7P
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